Appendix A: Derivation of equations 4 and 7.

Deriving equations 4 and 7 requires some knowledge of ordinary differential equations, which many ecologists may not be familiar with. Therefore, we include a brief description here.

Equation 4. We begin with:

$$\frac{dp}{dt} = bp + c \tag{A.1}$$

because a in equation (1) is set to zero. One way of finding the function, p, in terms of t, that satisfies the above equation is to first define a new function q as,

$$q = p + c/b \tag{A.2}$$

Note that derivatives of p and q with respect to time are identical because neither c nor b varies with time. As a consequence, we can rewrite equation A.1 as,

$$\frac{dq}{dt} = bq \tag{A.3}$$

It can then be shown that the following equation for q satisfies A.3.

$$q(t) = ke^{bt} \tag{A.4}$$

where k is a constant. Reinserting this in equation A.2 and solving for p, we arrive at:

$$p(t) = ke^{bt} - c/b \tag{A.5}$$

Substituting $b = -(\gamma + \varepsilon)$, and $c = \gamma$ we get.

$$p(t) = ke^{-(\gamma+\varepsilon)t} + \frac{\gamma}{\gamma+\varepsilon}$$
(A.6)

Note that (A.6) differs only from equation 4 in the manuscript in that we have applied the initial condition that p(0) = 0 and solved for $k = -\frac{\gamma}{\gamma + \varepsilon}$.

Modeling declines. Equation A.6 could also be used to describe the dynamics of decline. For example, if the underlying colonization and extinction rates change such that the initial occupancy, p_i , is greater than the equilibrium values implied by the new colonization and extinction rates, then the dynamics of the decline can be modelled simply by substituting $k = p_i - \frac{\gamma}{\gamma + \varepsilon}$ into equation A.6. Extending this to look at different scenarios for the transient dynamics of A and R during a decline in two environments is straightforward.

Equation 7. We begin with the equation,

$$\frac{dp}{dt} = ap^2 + bp + c \tag{A.7}$$

with *a*<0, *b*>0 and *c*>0. Equation A.7 can be written in terms of its roots, λ , and λ_{i} , as:

$$\frac{dp}{dt} = a(p - \lambda_{\prime})(p - \lambda_{\prime\prime})$$
(A.8)

which can be split into the following partial fractions:

$$\frac{1}{dp/dt} = a^{-1} \left(\frac{A}{p-\lambda_{\prime}} + \frac{B}{p-\lambda_{\prime\prime}} \right)$$
(A.8)

where $A = 1/(\lambda_{I} - \lambda_{II}) = -B$. We can then replace A with -B and rearrange A.8 to get:

$$\frac{a}{A}dt = \frac{dp}{p-\lambda_{\prime}} - \frac{dp}{p-\lambda_{\prime\prime}}$$
(A.9)

and integrate both sides to get,

$$\frac{a}{A}t + k = \ln|p - \lambda_{\prime}| - \ln|p - \lambda_{\prime\prime}| = \ln\left|\frac{p - \lambda_{\prime}}{p - \lambda_{\prime\prime}}\right|$$
(A.10)

Since *c*>0, this implies that *p* is slightly positive in the neighborhood of zero, therefore we know that in this neighborhood $\lambda_i , and thus we can rewrite A.10 as,$

$$\frac{a}{A}t + k = ln\left(\frac{p-\lambda_{I}}{\lambda_{II}-p}\right)$$
(A.11)

which is equivalent to

$$Ke^{\frac{a}{A}t} = \frac{p-\lambda}{\lambda''-p}$$
(A.12)

where $K = e^k$. The initial condition p(0) = 0, imples that $K = \frac{-\lambda}{\lambda''}$. Inserting this value of K into A.12, as well as replacing A with $1/(\lambda_i - \lambda_{ii})$ leads to equation 7 in the main text.